SIEMENS



Data sheet 3RW5527-3HA04



SIRIUS soft starter 200-480 V 93 A, 24 V AC/DC spring-type terminals

| product brand name | SIRIUS |
|---------------------------------------------------------------------------------------------------|------------------------------------------------------------------|
| product category | Hybrid switching devices |
| product designation | Soft starter |
| product type designation | 3RW55 |
| manufacturer's article number | |
| of high feature HMI module usable | 3RW5980-0HF00 |
| of communication module PROFINET standard usable | 3RW5980-0CS00 |
| of communication module PROFINET high-feature usable | 3RW5950-0CH00 |
| of communication module PROFIBUS usable | 3RW5980-0CP00 |
| of communication module Modbus TCP usable | 3RW5980-0CT00 |
| of communication module Modbus RTU usable | 3RW5980-0CR00 |
| of communication module Ethernet/IP | 3RW5980-0CE00 |
| of circuit breaker usable at 400 V | 3VA2216-7MN32-0AA0; Type of coordination 1, Iq = 15 kA, CLASS 10 |
| of circuit breaker usable at 500 V | 3VA2216-7MN32-0AA0; Type of coordination 1, Iq = 10 kA, CLASS 10 |
| of circuit breaker usable at 400 V at inside-delta circuit | 3VA2220-7MN32-0AA0; Type of coordination 1, Iq = 15 kA, CLASS 10 |
| of circuit breaker usable at 500 V at inside-delta circuit | 3VA2220-7MN32-0AA0; Type of coordination 1, Iq = 10 kA, CLASS 10 |
| of the gG fuse usable up to 690 V | 3NA3136-6; Type of coordination 1, Iq = 65 kA |
| of the gG fuse usable at inside-delta circuit up to 500 V | 3NA3136-6; Type of coordination 1, Iq = 65 kA |
| of full range R fuse link for semiconductor protection usable up to 690 V | 3NE1224-0; Type of coordination 2, Iq = 65 kA |
| of back-up R fuse link for semiconductor protection usable up to 690 V | 3NE3227: Type of coordination 2, Iq = 65 kA |

| General technical data | |
|------------------------------------------|----------------------|
| starting voltage [%] | 20 100 % |
| stopping voltage [%] | 50 %; non-adjustable |
| start-up ramp time of soft starter | 0 360 s |
| ramp-down time of soft starter | 0 360 s |
| start torque [%] | 10 100 % |
| stopping torque [%] | 10 100 % |
| torque limitation [%] | 20 200 % |
| current limiting value [%] adjustable | 125 800 % |
| breakaway voltage [%] adjustable | 40 100 % |
| breakaway time adjustable | 0 2 s |
| number of parameter sets | 3 |
| accuracy class according to IEC 61557-12 | 5 % |
| certificate of suitability | |

| CE marking | Yes Yes Yes |
|----------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| UL approval | Yes |
| CSA approval | Yes |
| product component | |
| HMI-High Feature | Yes |
| is supported HMI-High Feature | Yes |
| product feature integrated bypass contact system | Yes |
| number of controlled phases | 3 |
| trip class | CLASS 10A / 10E (default) / 20E / 30E; acc. to IEC 60947-4-2 |
| current unbalance limiting value [%] | 10 60 % |
| ground-fault monitoring limiting value [%] | 10 95 % |
| buffering time in the event of power failure | |
| for main current circuit | 100 ms |
| for control circuit | 100 ms |
| idle time adjustable | 0 255 s |
| insulation voltage rated value | 480 V |
| degree of pollution | 3, acc. to IEC 60947-4-2 |
| impulse voltage rated value | 6 kV |
| blocking voltage of the thyristor maximum | 1 400 V |
| service factor | 1.15 |
| surge voltage resistance rated value | 6 kV |
| maximum permissible voltage for safe isolation | |
| between main and auxiliary circuit | 480 V; does not apply for thermistor connection |
| shock resistance | 15 g / 11 ms, from 6 g / 11 ms with potential contact lifting |
| vibration resistance | 15 mm up to 6 Hz; 2 g up to 500 Hz |
| recovery time after overload trip adjustable | 60 1 800 s |
| utilization category according to IEC 60947-4-2 | AC 53a |
| reference code according to IEC 81346-2 | Q |
| Substance Prohibitance (Date) | 02/15/2018 |
| product function | |
| ramp-up (soft starting) | Yes |
| ramp-down (soft stop) | Yes |
| breakaway pulse | Yes |
| adjustable current limitation | Yes |
| creep speed in both directions of rotation | Yes |
| pump ramp down | Yes |
| DC braking | Yes |
| motor heating | Yes |
| slave pointer function | Yes |
| trace function | Yes |
| intrinsic device protection | Yes |
| motor overload protection | Yes; Full motor protection (thermistor motor protection and electronic motor overload protection) / When using the motor overload protection according to ATEX, an upstream contactor is required in inside-delta circuit. |
| evaluation of thermistor motor protection | Yes; Type A PTC or Klixon / Thermoclick |
| • inside-delta circuit | Yes |
| • auto-RESET | Yes |
| manual RESET | Yes |
| remote reset | Yes |
| communication function | Yes |
| operating measured value display | Yes |
| event list | Yes |
| error logbook | Yes |
| • via software parameterizable | Yes |
| • via software configurable | Yes |
| screw terminal | No |
| spring-loaded terminal | Yes |
| PROFlenergy | Yes; in connection with the PROFINET Standard and PROFINET High- Feature communication modules |
| firmware update | Yes |

| removable terminal for control circuit | Yes |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| voltage ramp | Yes Yes Yes |
| torque control | Yes |
| combined braking | Yes |
| analog output | Yes; 4 20 mA (default) / 0 10 V |
| programmable control inputs/outputs | Yes |
| condition monitoring | Yes |
| automatic parameterisation | Yes |
| application wizards | Yes |
| alternative run-down | Yes |
| emergency operation mode | Yes |
| reversing operation | Yes |
| soft starting at heavy starting conditions | Yes |
| Power Electronics | |
| operational current | |
| at 40 °C rated value | 93 A |
| at 40 °C rated value minimum | 19 A |
| at 50 °C rated value | 82.5 A |
| at 60 °C rated value | 75.5 A |
| operational current at inside-delta circuit | |
| • at 40 °C rated value | 161 A |
| at 50 °C rated value | 143 A |
| at 60 °C rated value | 131 A |
| operating voltage | |
| • rated value | 200 480 V |
| at inside-delta circuit rated value | 200 480 V |
| relative negative tolerance of the operating voltage | -15 % 10 % |
| relative positive tolerance of the operating voltage relative negative tolerance of the operating voltage at | -15 % |
| inside-delta circuit | -13 /0 |
| relative positive tolerance of the operating voltage at inside-delta circuit | 10 % |
| operating power for 3-phase motors | |
| at 230 V at 40 °C rated value | 22 kW |
| at 230 V at inside-delta circuit at 40 °C rated value | 45 kW |
| at 400 V at 40 °C rated value | 45 kW |
| at 400 V at inside-delta circuit at 40 °C rated value | 90 kW |
| Operating frequency 1 rated value | 50 Hz |
| Operating frequency 2 rated value | 60 Hz |
| | |
| relative negative tolerance of the operating frequency | -10 % |
| relative positive tolerance of the operating frequency | -10 % 10 % |
| relative positive tolerance of the operating frequency minimum load [%] | -10 % |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC | -10 % 10 % 10 %; Relative to set le |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup | -10 % 10 % 10 %; Relative to set le |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup | -10 % 10 % 10 %; Relative to set le 28 W 25 W |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup | -10 % 10 % 10 %; Relative to set le |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 % | -10 % 10 % 10 %; Relative to set le 28 W 25 W 23 W |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 % • at 40 °C during startup | -10 % 10 %; Relative to set le 28 W 25 W 23 W |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 % • at 40 °C during startup • at 50 °C during startup | -10 % 10 % 10 %; Relative to set le 28 W 25 W 23 W |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 % • at 40 °C during startup | -10 % 10 % 10 %; Relative to set le 28 W 25 W 23 W 1 258 W 1 065 W 948 W |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup power loss [W] at AC at current limitation 350 % • at 40 °C during startup • at 50 °C during startup • at 60 °C during startup | -10 % 10 % 10 %; Relative to set le 28 W 25 W 23 W 1 258 W 1 065 W |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 % • at 40 °C during startup • at 50 °C during startup • at 60 °C during startup type of the motor protection Control circuit/ Control | -10 % 10 % 10 %; Relative to set le 28 W 25 W 23 W 1 258 W 1 065 W 948 W |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 % • at 40 °C during startup • at 50 °C during startup • at 60 °C during startup type of the motor protection | -10 % 10 %; Relative to set le 28 W 25 W 23 W 1 258 W 1 065 W 948 W Electronic, tripping in the event of thermal overload of the motor |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 % • at 40 °C during startup • at 50 °C during startup • at 60 °C during startup type of the motor protection Control circuit/ Control type of voltage of the control supply voltage | -10 % 10 %; Relative to set le 28 W 25 W 23 W 1 258 W 1 065 W 948 W Electronic, tripping in the event of thermal overload of the motor |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 % • at 40 °C during startup • at 50 °C during startup • at 60 °C during startup type of the motor protection Control circuit/ Control type of voltage of the control supply voltage control supply voltage at AC | -10 % 10 %; Relative to set le 28 W 25 W 23 W 1 258 W 1 065 W 948 W Electronic, tripping in the event of thermal overload of the motor |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 % • at 40 °C during startup • at 50 °C during startup • at 60 °C during startup type of the motor protection Control circuit/ Control type of voltage of the control supply voltage control supply voltage at AC • at 50 Hz rated value | -10 % 10 %; Relative to set le 28 W 25 W 23 W 1 258 W 1 065 W 948 W Electronic, tripping in the event of thermal overload of the motor |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 % • at 40 °C during startup • at 50 °C during startup • at 60 °C during startup type of the motor protection Control circuit/ Control type of voltage of the control supply voltage control supply voltage at AC • at 50 Hz rated value • at 60 Hz rated value relative negative tolerance of the control supply | -10 % 10 %; Relative to set le 28 W 25 W 23 W 1 258 W 1 065 W 948 W Electronic, tripping in the event of thermal overload of the motor |
| relative positive tolerance of the operating frequency minimum load [%] power loss [W] for rated value of the current at AC • at 40 °C after startup • at 50 °C after startup • at 60 °C after startup power loss [W] at AC at current limitation 350 % • at 40 °C during startup • at 50 °C during startup • at 60 °C during startup type of the motor protection Control circuit/ Control type of voltage of the control supply voltage control supply voltage at AC • at 50 Hz rated value relative negative tolerance of the control supply voltage at AC at 50 Hz relative positive tolerance of the control supply | -10 % 10 %; Relative to set le 28 W 25 W 23 W 1 258 W 1 065 W 948 W Electronic, tripping in the event of thermal overload of the motor AC/DC 24 V 24 V -20 % |

| voltage at AC at 60 Hz | ov dientudena |
|-------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| relative positive tolerance of the control supply voltage at AC at 60 Hz | ^{20 %} dientudong |
| control supply voltage frequency | 50 60 Hz |
| relative negative tolerance of the control supply voltage frequency | -10 % |
| relative positive tolerance of the control supply voltage frequency | 10 % |
| control supply voltage | |
| at DC rated value | 24 V |
| relative negative tolerance of the control supply voltage at DC | -20 % |
| relative positive tolerance of the control supply voltage at DC | 20 % |
| control supply current in standby mode rated value | 440 mA |
| holding current in bypass operation rated value | 870 mA |
| locked-rotor current at close of bypass contact maximum | 6.3 A |
| inrush current peak at application of control supply voltage maximum | 7.5 A |
| duration of inrush current peak at application of control supply voltage | 20 ms |
| design of the overvoltage protection | Varistor |
| design of short-circuit protection for control circuit | 4 A gG fuse (Icu=1 kA), 6 A quick-acting fuse (Icu=1 kA), C1 miniature circuit breaker (Icu= 600 A), C6 miniature circuit breaker (Icu= 300 A); Is not part of scope of supply |
| Inputs/ Outputs | |
| number of digital inputs | 4 |
| parameterizable | 4 |
| number of digital outputs | 4 |
| number of digital outputs parameterizable | 3 |
| number of digital outputs not parameterizable | 1 |
| digital output version | 3 normally-open contacts (NO) / 1 changeover contact (CO) |
| number of analog outputs | 1 |
| switching capacity current of the relay outputs | |
| at AC-15 at 250 V rated value | 3 A |
| at DC-13 at 24 V rated value | 1 A |
| Installation/ mounting/ dimensions | |
| mounting position | Vertical (can be rotated +/- 90° and tilted forward or backward +/- 22.5°) |
| fastening method | screw fixing |
| height | 306 mm |
| width | 185 mm |
| depth | 203 mm |
| required spacing with side-by-side mounting | |
| forwards | 10 mm |
| backwards | 0 mm |
| • upwards | 100 mm |
| downwards | 75 mm |
| • at the side | 5 mm |
| weight without packaging | 7.15 kg |
| Connections/ Terminals | |
| type of electrical connection | |
| for main current circuit | box terminal |
| • for control circuit | spring-loaded terminals |
| width of connection bar maximum | 25 mm |
| wire length for thermistor connection | |
| • with conductor cross-section = 0.5 mm² maximum | 50 m |
| • with conductor cross-section = 1.5 mm² maximum | 150 m |
| with conductor cross-section = 2.5 mm² maximum | 250 m |
| type of connectable conductor cross-sections | 4 (0.5 40 0) |
| for main contacts for box terminal using the front clamping point solid | 1x (2.5 16 mm²) |

| for main contacts for box terminal using the front clamping point finely stranded with core end processing | 1x (2.5 50 mm²) dientudong |
|----------------------------------------------------------------------------------------------------------------------------------------|-------------------------------------------------------------------------------------------------------------------------|
| for main contacts for box terminal using the front clamping point stranded | 1x (10 70 mm²) |
| at AWG cables for main contacts for box terminal using the front clamping point | 1x (10 2/0) |
| for main contacts for box terminal using the back clamping point solid | 1x (2.5 16 mm²) |
| at AWG cables for main contacts for box terminal using the back clamping point | 1x (10 2/0) |
| for main contacts for box terminal using both clamping points solid | 2x (2.5 16 mm²) |
| for main contacts for box terminal using both clamping points finely stranded with core end processing | 2x (2.5 35 mm²) |
| for main contacts for box terminal using both clamping points stranded | 2x (6 16 mm²), 2x (10 50 mm²) |
| for main contacts for box terminal using the back clamping point finely stranded with core end processing | 1x (2.5 50 mm²) |
| for main contacts for box terminal using the back clamping point stranded | 1x (10 70 mm²) |
| type of connectable conductor cross-sections | |
| for control circuit solid | 2x (0.25 1.5 mm²) |
| for control circuit finely stranded with core end processing | 2x (0.25 1.5 mm²) |
| at AWG cables for control circuit solid | 2x (24 16) |
| at AWG cables for control circuit finely stranded with core end processing | 2x (24 16) |
| wire length | |
| between soft starter and motor maximum | 800 m |
| at the digital inputs at DC maximum | 1 000 m |
| tightening torque | |
| for main contacts with screw-type terminals | 4.5 6 N·m |
| for auxiliary and control contacts with screw-type terminals | 0.8 1.2 N·m |
| tightening torque [lbf·in] | |
| for main contacts with screw-type terminals | 40 53 lbf·in |
| for auxiliary and control contacts with screw-type terminals | 7 10.3 lbf·in |
| Ambient conditions | |
| | 5.000 m. Danetin and 4.000 m. and anti-lan |
| installation altitude at height above sea level maximum | 5 000 m; Derating as of 1000 m, see catalog |
| ambient temperature | OF 100 °C. Places shown a densiting at temporatures of 40 °C or |
| during operation | -25 +60 °C; Please observe derating at temperatures of 40 °C or above |
| during storage and transport | -40 +80 °C |
| environmental category | |
| during operation according to IEC 60721 | 3K6 (no ice formation, only occasional condensation), 3C3 (no salt mist), 3S2 (sand must not get into the devices), 3M6 |
| during storage according to IEC 60721 | 1K6 (only occasional condensation), 1C2 (no salt mist), 1S2 (sand must not get inside the devices), 1M4 |
| during transport according to IEC 60721 | 2K2, 2C1, 2S1, 2M2 (max. fall height 0.3 m) |
| EMC emitted interference | acc. to IEC 60947-4-2: Class A |
| Communication/ Protocol | |
| communication module is supported | |
| PROFINET standard | Yes |
| PROFINET high-feature | Yes |
| EtherNet/IP | Yes |
| Modbus RTU | Yes |
| Modbus TCP | Yes |
| PROFIBUS | Yes |
| UL/CSA ratings | |
| manufacturer's article number | |
| | |

of circuit breaker

 usable for Standard Faults at 460/480 V according to UL

- usable for High Faults at 460/480 V according to UL

- usable for Standard Faults at 460/480 V at inside-delta circuit according to UL

- usable for High Faults at 460/480 V at insidedelta circuit according to UL

- usable for Standard Faults at 575/600 V according to UL

 usable for High Faults at 575/600 V at insidedelta circuit according to UL

- usable for Standard Faults at 575/600 V at inside-delta circuit according to UL

- usable for Standard Faults up to 575/600 V according to UL

 usable for High Faults up to 575/600 V according to UL

- usable for Standard Faults at inside-delta circuit up to 575/600 V according to UL

- usable for High Faults at inside-delta circuit up to 575/600 V according to UL

Siemens type: 3VA



Siemens type: 3VA51, max. 125 A; Iq = 10 kA

Siemens type: 3VA51, max. 125 A; Iq max = 65 kA

Siemens type: 3VA51, max. 125 A; Iq = 10 kA

Siemens type: 3VA51, max. 125 A; Iq max = 65 kA

Siemens type: 3VA51, max. 125 A; Iq = 10 kA

Type: Class RK5 / K5, max. 300 A; Iq = 10 kA

Type: Class J / L, max. 250 A; Iq = 100 kA

Type: Class RK5 / K5, max. 300 A; Iq = 10 kA

Type: Class J / L, max. 250 A; Iq = 100 kA

operating power [hp] for 3-phase motors

• at 200/208 V at 50 °C rated value

• at 220/230 V at 50 °C rated value

• at 460/480 V at 50 °C rated value

• at 200/208 V at inside-delta circuit at 50 °C rated

• at 220/230 V at inside-delta circuit at 50 °C rated value

• at 460/480 V at inside-delta circuit at 50 °C rated value

25 hp

30 hp

60 hp 40 hp

50 hp

100 hp

contact rating of auxiliary contacts according to UL

R300-B300

protection class IP on the front according to IEC

touch protection on the front according to IEC 60529

electromagnetic compatibility

IP00; IP20 with cover

acc. to IEC 60947-4-2

finger-safe, for vertical contact from the front with cover

ATEX

certificate of suitability

ATEX

Safety related data

IECEx

Yes

Yes

according to ATEX directive 2014/34/EU

type of protection according to ATEX directive 2014/34/EU

BVS 18 ATEX F 003 X

II (2)G [Ex eb Gb] [Ex db Gb] [Ex pxb Gb], II (2)D [Ex tb Db] [Ex pxb Db], I (M2) [Ex db Mb]

hardware fault tolerance according to IEC 61508 relating to ATEX

PFDavg with low demand rate according to IEC 61508

relating to ATEX

PFHD with high demand rate according to EN 62061 relating to ATEX

Safety Integrity Level (SIL) according to IEC 61508 relating to ATEX T1 value for proof test interval or service life

according to IEC 61508 relating to ATEX

5E-7 1/h

0.008

SIL₁

3s

Certificates/ approvals

General Product Approval

EMC





Confirmation









For use in hazardous locations

Declaration of Conformity





Type Test Certificates/Test Report





Marine / Shipping

other







Confirmation

Information- and Downloadcenter (Catalogs, Brochures,...)

https://www.siemens.com/ic10

Industry Mall (Online ordering system)

https://mall.industry.siemens.com/mall/en/en/Catalog/product?mlfb=3RW5527-3HA04

Cax online generator

http://support.automation.siemens.com/WW/CAXorder/default.aspx?lang=en&mlfb=3RW5527-3HA04

Service&Support (Manuals, Certificates, Characteristics, FAQs,...)

https://support.industry.siemens.com/cs/ww/en/ps/3RW5527-3HA04

Image database (product images, 2D dimension drawings, 3D models, device circuit diagrams, EPLAN macros, ...)

http://www.automation.siemens.com/bilddb/cax_de.aspx?mlfb=3RW5527-3HA04&lang=en

Characteristic: Tripping characteristics, I2t, Let-through current

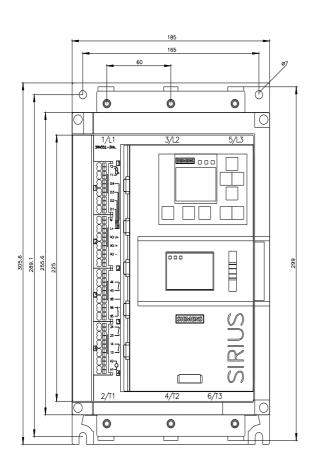
https://support.industry.siemens.com/cs/ww/en/ps/3RW5527-3HA04/char

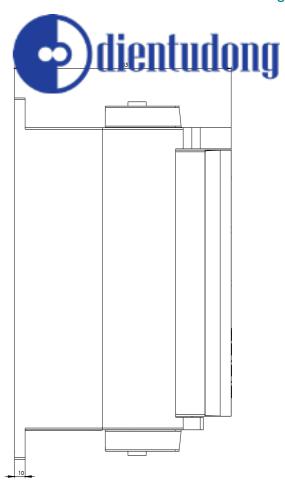
Characteristic: Installation altitude

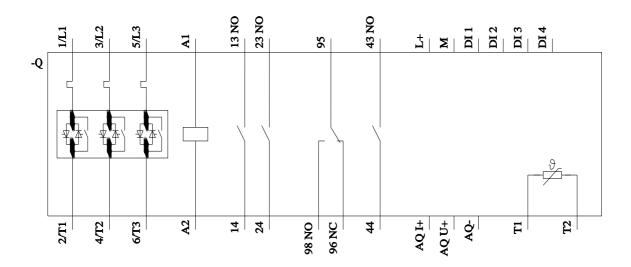
http://www.automation.siemens.com/bilddb/index.aspx?view=Search&mlfb=3RW5527-3HA04&objecttype=14&gridview=view1

Simulation Tool for Soft Starters (STS)

https://support.industry.siemens.com/cs/ww/en/view/101494917







Hotline: 0909000786 - lam@dientudong.com



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